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Cost-Effective dynamic fair priority algorithm for task scheduling in cloud computing environment

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Abstract

Cloud computing is an emerging trends in distributed computing which offers pay per model as user demand and constraint. Cloud applications having variety of composition, configuration, and deployment supplies. To quantify the performance of resource allocation policies and application scheduling algorithms at finer details in Cloud computing environments for different application and service modules under varying load, energy performance. system size is a challenging problem to tackle Cloud consist of a group of virtual machine which includes both computational and storage space facility. The primary aim of cloud computing is to provide better resourceful access. Cloud computing is based on the concept of distributed computing, grid computing, and virtualization techniques. Cloud is developing day by day and faces a lot of challenges, one of them is scheduling. Scheduling refers to a set of policies to control the order of works to be performed by a computer system. The CloudSim toolkit supports creation of one or supplementary virtual machines (VMs) on a simulated node of a Data Center, jobs, and their mapping to fitting VMs. It also allows simulation of multiple Data Centers to enable a study on federation and associated policies for migration of VMs for reliability and automatic scaling of applications. A first-class scheduler adapts its scheduling strategy according to the changing environment and the type of task. In paper we presented a Dynamic Fair Priority Task Scheduling Algorithm for efficient execution of task and comparison with FCFS and Round Robin Scheduling. Algorithm should be tested in cloud Sim toolkit and result shows that it give better performance compared to other conventional scheduling algorithm.

Keywords: cloud Computing, scheduling, Data Center, Virtual machine, Task scheduling

1. Introduction

Cloud computing comes in concern development of the grid computing, virtualization and web technologies. Cloud computing is an internet based computing that delivers infrastructure as a service (IaaS), platform as a service (PaaS), and software as services (SaaS). In SaaS, software application is made available by the cloud provider. In PaaS an application development platform is provided as a service to the developer to create a web based application. In IaaS computing infrastructure is provided as a service to the requester in the form of Virtual Machine (VM). These services are made available on a subscription basis using pay as-you-use replication to customers, in any case of their location. Cloud Computing still under in its development stage and has many issues and challenges out of the various issues in cloud scheduling plays very important role in determining the effective execution. Scheduling refers to the set of policies to control the order of work to be performed by a computer system. There has been various types of scheduling algorithm existing in distributed computing system, and job scheduling is one of them. The main advantage of job scheduling algorithm is to achieve a high performance computing and the system throughput. Scheduling manage ease of use of CPU memory and good scheduling policy gives maximum utilization of resource. We compared three algorithm Time Shared, Space shred and generalizes priority algorithm.

Relatedwork

In this section, we describe the related work ok task scheduling in cloud computing environment.

In paper [1] presented a short description of cloud Sim toolkit and his operation. Cloud Sim toolkit is a platform where you can test your job before applied into real work, here we learn how to simulate a task with different approaches and different scheduling policy.

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In paper [2] author proposed an approach for task scheduling algorithm based on load balancing in cloud computing. This paper described two level task scheduling based on the load balancing. This type of task scheduling cannot only meet user's requirement but also provide resource utilization. This paper presented the completing of an efficient Quality of Service (QoS) base on Meta-Scheduler and Backfill method depends upon a light weight Virtual Machine Scheduler for dispatching jobs

In paper [3] presented an optimized algorithm for task scheduling based on genetic simulated annealing algorithm. This considers the QoS supplies like work time, band width, cost, distance, reliability of different type tasks. Here annealing is implemented after the selection, crossover and mutation, to improve local search ability of genetic algorithm.

In paper [4] hierarchical scheduling is presented which helps in achieving Service Level Agreement with quick response from the service provider. In our proposed approach Quality of Service metric such as response time is achieved by running the high precedence jobs (deadline based jobs) first by estimate job over time and the priority tasks are spawned from the un completed job with the help of Task Scheduler.

In paper [5] author presented an optimized algorithm for task scheduling based on Activity Based Costing (ABC). This algorithm assigns priority point for each task and uses cost drivers. ABC procedures both cost of the object and show of the activities.

In paper [6] presented transaction intensive cost constraint cloud Work flow scheduling algorithm. consider execution charge and running time as the two main key consideration. The algorithm minimize the cost under certain user designated deadlines. Our proposed methodology is mainly based on computational capability of Virtual Machines.

In paper [7] a new VM Load Balancing Algorithm is Weighted Active Monitoring Load Balancing Algorithm using Cloud Sim tools, for the Datacenter to effectively load balance requests between the available virtual machines assigning a weight, in classify to done resourceful performance parameter. Here VMs of different processing jobs and the tasks/requests are assigned or due to the most controlling VM and then to the lowest and so once

In paper [8] author proposed an algorithm is Antcolony optimization in which random optimization find method is used for allocating the incoming jobs to the virtual machines This algorithm uses a positive feedback method and imitates the behavior of real ant colonies in nature to search for food and to join to each extra by pheromone laid on paths traveled.

In paper [9] is analyzing and evaluating the performance of various CPU scheduling in cloud environment using Cloud Sim the basic algorithm OS like as FCFS, Priority arrangement and Shortest Job First, we test under different which scheduling policy perform better

In paper [10] author proposes a priority based on dynamic resource allowance in cloud computing. This paper considers the a number of SLA restriction and resource allotment by pre-emption mechanism for high

priority task execution can improve the resource utilization in cloud. The main features of the paper is that it providing dynamic resource provisioning and attains multiple SLA objectives are done through priority based scheduling method. Since cost is the important aspect in cloud computing

Future work

In This paper we generally discuss three algorithm we developed a Dynamic Fair Priority Task Scheduling Algorithm with limited task edition, future we will take further task and try to shrink the execution time as presented and we invented this algorithm to grid environment and will monitor the difference of time in cloud an grid.

3.1 Scheduling model

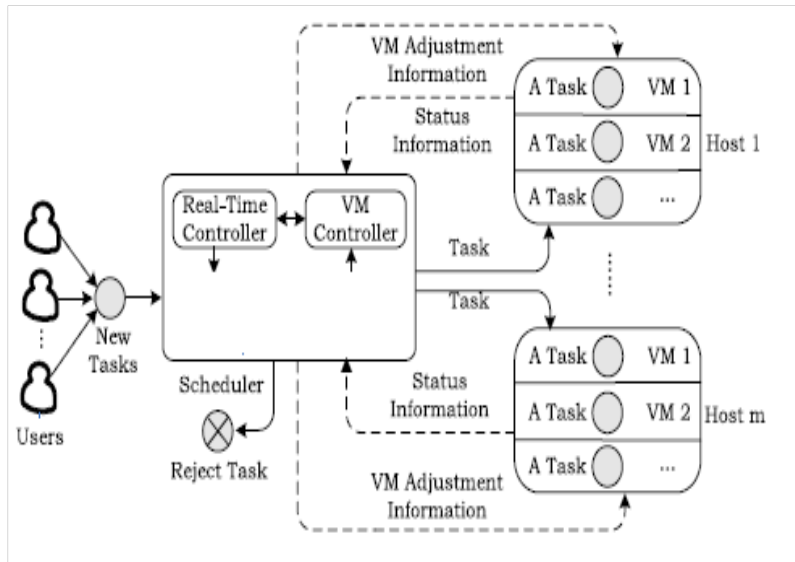
We object a virtualized cloud that is characterized by an infinite set of physical computing hosts offering the hardware infrastructure for creating virtualized resources to assure users' requirements

When a new task arrives, the scheduling process follows five steps as below:

- 1) The scheduler verify the system status information Such as parallel running tasks' remaining execution time and, VMs' deployments, and the information of tasks in waiting the task deadlines, and currently allocated VMs, starting time.
- 2) The tasks in rolling-horizon are arranged by their deadlines to facilitate to the scheduling operation.
- 3) The real-time controller regulate whether a task in the rolling-horizon can be done before its deadline. then VM controller adds VMs to finish the task within that timing constraints.
- 4) The scheduling decision for the tasks in the rolling-horizon is updated to scheduler.

When a task in the rolling-horizon is complete to execute means,

the task is dispatched and to assigned VM.



3.2 Task model

Task model is used to approximate a actual queuing situation or system, so the queuing actions can be analyzed mathematically. Queuing models access a number of useful steady state performance actions to be determined. mainly described by the notation A/B/C/D/E. A- Distribution of inter arrival times of customers; B- Distribution of service times; C- Number of servers; D- Maximum total number of customers which can be accommodated in system, i.e. system capacity; E- Queuing discipline. Let’s take an example where M/M/m/K/N- this would describe a queuing system with an exponential distribution for the inter arrival times of customers and the service times of customers, m servers, a highest of K customers in the queuing system at one after, and potential customers in the called population. There are a lot of models available like M/M/1, M/M/2, etc. however we describe our model in M/M/2 structure

- 1) Here considered each request as a task and it is also very much important to inter task communication in some cases, so the task will have integrity itself and data transfer among the tasks will be minimized.
- 2) The amount of working out mandatory by each task and speed of each processor or resource are known.
- 3) The cost of processing each task on every resource of the system is known. The cost usually derived based on the information about the speed of each processor and amount of computation required by each task.
- 4) The Intercrosses Communication (IPC) costs between every pair of tasks are known. The IPC cost is negligible or zero for task assigned to the same node. They are usually estimated by an analysis static program of a process. Suppose two task communicate n times and if the average time for each inter-task communication is t, the inter-task communication cost for the two tasks is n*t.
- 5) Resource requirement of the tasks; the availability of resources and precedence relationship among the task also need to be known. F) The main constrain of the model is that reassignment of the task is generally not possible

4. Performance Analysis

In this section describe Dynamic Fair Priority Task Scheduling Algorithm algorithms and describe the procedure of the

assignment of task into the resources. If there are m number of tasks and q number of resources, then there are my possible assignments of tasks to resources. However, the actual number of possible assignments of tasks to resources may be less than my due to the restriction that certain tasks cannot be assigned to certain resources due to their specific resource requirements. Dynamic Fair Priority Task Scheduling Algorithm must recover those assignment problems. Before start to describe the algorithms we consider that there are six task {T1, T2, T3, T4, T5, T6} and two resources {R1, R2} are available. Using the Dynamic Fair Priority Task Scheduling Algorithm algorithms we assign the six tasks into two resources such a way that total assignment cost must be optimum.

4.1. Serial Task Assignment Approach:-

In Dynamic Fair Priority Task Scheduling Algorithm approach tasks must be assigned to the available resources serially. Means first few number tasks assigns to resource 1, next to resource 2 and so on. In this way all the tasks are assigned to all the resources serially. For example if consider table 1 and table 2 then get another table 4.1, where the procedure of Dynamic Fair Priority Task Scheduling Algorithm is discussed. Table 4.1 shows a serial assignment of the tasks to the two resources in which first three tasks are assigned to resource R1 and remaining three are assigned to resource R2. This assignment is aimed at minimizing the total execution costs. But we must to consider the execution cost as well as inter process communication cost which must be shown below This assignment is aimed at optimizing the total execution costs. But here also we must need to consider the execution cost as well as inter-process communication cost which must be shown below

Table 4.1: Serial Assignment

TASK	RESOURCE
T1	R1
T2	R2
T3	R3
T4	R4
T5	R5
T6	R6

Serial Assignment Execution Cost = $X_{11}+X_{21}+X_{31}+X_{42}+X_{52}+X_{62} = 5+2+4+3+2+4 = 20$
 Serial Assignment Communication Cost = $C_{14}+C_{15}+C_{16}+C_{24}+C_{25}+C_{26}+C_{34}+C_{35}+C_{36} = 0+0+12+12+3+0+0+11+0 = 38$
 Serial Assignment Total Cost = $X+C = 20+38 = 58$ So total serial assignment cost is 58 in case of DYNAMIC FAIR PRIORITY TASK SCHEDULING ALGORITHM algorithms. To reduce the total assignment cost next section we describe another TAA algorithm.

4.2. Optimal Task Assignment Approach:-

In Dynamic Fair Priority Task Scheduling Algorithm the problem of finding an assignment of task to resources that minimize the total execution and communication cost elegantly analyzed using a network flow model and network flow algorithm. In this approach, an optimal assignment is found by creating static assignment graph. Using the above procedure every task must be assign to every other resource; those resources are available to reduce the overall cost of the system. For example if consider the table 4.1 and table 4. 2 then get another table 4, where produce Dynamic Fair Priority Task Scheduling Algorithm is discussed. Table 4.2 shows a optimal assignment of the task to the two resources using the procedure of network flow graph and network flow algorithm. So first five tasks T1 to T5 must be assigned to resource R1 and task T6 only assign to resource R6.

Table 4.2: Optimal Assignment

TASK	RESOURCE
T1	R1
T2	R1
T3	R1
T4	R1
T5	R1
T6	R2

Optimal Assignment Execution Cost = $X_{11}+X_{21}+X_{31}+X_{41}+X_{51}+X_{62} = 5+2+4+6+5+4 = 26$
 Optimal Assignment Communication Cost = $C_{16}+C_{26}+C_{36}+C_{46}+C_{56} = 12+0+0+0+0 = 12$
 Optimal Assignment Total Cost = $X+C = 26+12 = 38$ So in case of OTAA overall assignment cost must be reduced to 38; which is too much smaller compare to STAA where total serial assignment costs are 58.

Conclusion

Scheduling is one of the the majority important tasks in cloud computing environment and we analyzed a variety of scheduling algorithm which powerfully schedules the computational tasks in cloud environment. We have produced FCFS, Round robin scheduling Algorithm and novel proposed Scheduling algorithm is Dynamic Fair Priority Task Scheduling Algorithm. Priority is an important concern of job scheduling in cloud environments. The experiment is conducted for changeable number of Virtual Machines and work load traces. The experiment conducted is compared with FCFS and Round Robin. The result shows that the proposed algorithm is further efficient than FCFS and Round Robin algorithm.

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